

Nimsoft Monitor Compatibility Matrix

December 20, 2013

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Compatibility Matrix

Last Updated: Dec/20/2013

Component	UMP 7.1	UMP 7.0	UMP 6.6	UMP 6.5	UMP 6.2	NMS 7.1	NMS 7.0	NMS 6.5	NMS 6.2	NMS 6.1	UR 7.1	UR 7.0	UR 6.5	UR 1.9
UR 7.1	✓	X	X	X	X	✓	X							
UR 7.0	X	✓	X	X	X	X	✓							
UR 6.5	X	X	✓	✓	X	X	X							
UR 1.9	X	X	X	X	✓	X	X							
NMS 7.1	✓	X	X	X	X						✓	X	X	X
NMS 7.0	X	✓	X	X	X						X	✓	X	X
NMS 6.5	X	X	✓	✓	X						X	X	✓	X
NMS 6.2	X	X	X	X	✓						X	X	X	✓
NMS 6.1	X	X	X	X	X						X	X	X	✓
Flow 1.1	X	X	✓	✓	✓	✓	✓	✓	✓	X	X	X		
Flow 1.0	X	X	X	X	✓	X	X	X	✓	✓	X	X		

Supported Upgrade Paths

This page highlights migration paths that are supported for the Nimsoft Unified Monitoring components.

Nimsoft Monitor Server (NMS)

NMS 5.61 → NMS 6.5 → NMS 7.1
NMS 6.5 → NMS 7.1
NMS 7.0 → NMS 7.1

Unified Management Portal (UMP)

UMP 2.6.2 → UMP6.6 → UMP 7.1
UMP 6.5 → UMP 7.1
UMP 6.6 → UMP 7.1
UMP 7.0 → UMP 7.1

Unified Reporter

UR 1.8 → UR 6.5 → UR 7.1
UR 6.5 → UR 7.1
UR 7.0 → UR 7.1

Component Support Matrix

Component	Operating Systems			Browsers			Databases			Java JRE
	Windows	Solaris	Linux	IE	Firefox	Chrome	Oracle	MySQL	MSSQL	
UMP 7.1	2008 (R2) (64 bit); 2012 R2 (64 bit)	10 / 11 SPARC and x86 64 bit only	Red Hat Linux 5 or 6, CentOS 5, 6, SUSE Enterprise Server 11 or 12 64bit	9, 10	19-26	24-31	11.2	5.5, 5.6	2008 R2, 2012	Java 6 or higher (JRE 1.6.26 Java 6 Version 26 recommended)
UMP 7.0	2008 (R2) (64 bit); 2012 (64 bit)	10 / 11 SPARC and x86 64 bit only	Red Hat Linux 5 or 6, CentOS 5, 6, SUSE Enterprise Server 11 or 12 64bit	9, 10	19, 20	24, 25	11.2	5.5, 5.6	2008 R2, 2012	Java 6 or higher (JRE 1.6.26 Java 6 Version 26 recommended)
UMP 6.6	2008 (R2) (64 bit) 2012 (64 bit)	10 SPARC and x86 64 bit only	Red Hat Linux 5 or 6, CentOS 5, 6, SUSE Enterprise Server 11 or 12 64bit	9 (32 bit, 64 bit) 10	11, 15, 18, 19	18, 24, 25	11.2	5.1, 5.5	2008 R2, 2012	Java 6 or higher (JRE 1.6.26 Java 6 Version 26 recommended)
UMP 6.5	2008 (R2) (64 bit) 2012 (64 bit)	10 SPARC and x86 64 bit only	Red Hat Linux 5 or 6, CentOS 5, 6, SUSE Enterprise Server 11 or 12 64bit	9 (32 bit, 64 bit)	11, 15, 18, 19	18, 24, 25	11.2	5.1, 5.5	2008 R2, 2012	Java 6 or higher (JRE 1.6.26 Java 6 Version 26 recommended)

Component	Operating Systems			Browsers			Databases			Java JRE
	Windows	Solaris	Linux	IE	Firefox	Chrome	Oracle	MySQL	MSSQL	
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NMS 7.0	2008 (R2) (64 bit); 2012 (64 bit)	10 / 11 SPARC and x86 64 bit	Red Hat Linux 5 or 6, CentOS 5, 6, SUSE Enterprise Server 11 or 12 64bit	9, 10	19- 20	24, 25	11.2	5.5, 5.6	2008 R2, 2012	Java 6 or higher (JRE 1.6.26 Java 6 Version 26 recommended)
NMS 6.5	2008 (R2) (64 bit); 2012 (64 bit)	10 / 11 SPARC and x86 64 bit	Red Hat Linux 5 or 6, CentOS 5, 6, SUSE Enterprise Server 10 or 11 (64 bit)	9, 10 (32 bit, 64 bit)	11, 12, 15	18	11.2	5.1, 5.5	2008 R2, 2012	Java 6 or higher (JRE 1.6.26 Java 6 Version 26 recommended)
NMS 6.2	2003, 2008 (R2) (32 and 64 bit)	10 / 11 SPARC and x86	Red Hat Linux 5 or 6, CentOS 5, 6, SUSE Enterprise Server 10 or 11	8, 9 (32 bit, 64 bit)	11, 12, 15	18	11.2	5.1, 5.5	2008 R2	Java 6 or higher (JRE 1.6.26 Java 6 Version 26 recommended)

Notes:

- Libstdc++.so.5 library is required for Linux OS

ADE

			Robot Deployment using the Automated Deployment Engine (ADE) Probe							
Supported Operating Systems			Deploy <i>from</i> (ADE host system, typically the NMS primary hub)							
			Windows Server			Linux			Solaris (10, 11)	
			2003	2008(R2)	2012	RHEL 5, 6	SUSE 11, 12	CentOS 5, 6	SPARC	x86, x86_64
Deploy <i>to</i> (target system)	Windows	7 32-bit	Yes			Note 1			Not supported	
		7 64-bit	Yes			Note 1				
		8 32-bit	Yes			Note 1				
		8 64-bit	Yes			Note 1				
		2003 32-bit	Yes			Note 1				
		2003 64-bit	Yes			Note 1				
		2008 32-bit	Yes			Notes 1 & 2				
		2008 64-bit	Yes			Notes 1 & 2				
		2012 64-bit	Yes			Notes 1 & 2				
	Linux	RHEL 5	Yes			Yes			Yes	
RHEL 6										
SUSE 11										

		SUSE 12	Yes	Yes	Yes			
		CentOS 5						
		CentOS 6						
		Debian 5						
		Debian 6						
		Ubuntu 10						
		Ubuntu 12						
	Solaris	Sol 10 & 11 SPARC 64				Yes	Yes	Yes
		Sol 10 & 11 x86, x86_64						
		Note 1: The Linux system must be joined to the domain of which the target system is a member.						
	Note 2: The recommended method of deploying a robot remotely to Windows 2008 is from ADE running on a <i>Windows</i> system. When deploying from <i>Linux</i> to Windows 2008, a method that requires a Windows registry configuration change is documented but not officially supported. If your environment requires deployment from Linux to Windows 2008, please contact CA Nimsoft Support for a KT document on this unsupported alternative.							